Two Axis Rate Turntable

Features

1. This kind of two-axis test turntable is part of a series of universal turntable top speed turntable with a range of standard modules available to customer's requirements. It can be selected according to customer's needs. It has position and speed functions to provide accurate single axis and double axis positioning and rate reference for the load to be measured. It is mainly used for static test and calibration of small and medium inertial measurement unit (IMU) and inertial navigation system.

2. This type of turntable shafts are directly driven by permanent magnet DC torque motor, the turntable shafts are directly driven by permanent magnet DC torque motor, PWM drive unit for the motor to provide the required power supply, so that the turntable has excellent rate stability and rate accuracy, accurate control precision in place.

3. The pitching shaft of the turntable is equipped with a mechanical locking device to facilitate the assembly and disassembly of the measured load. At the same time, when the mechanical locking device is in the locking state, the turntable's electric control system can not be put into operation, so as to avoid the motor damage caused by wrong operation.

4. The inner and outer frames of the turntable are equipped with conductive slip rings to facilitate the transmission of the measured load signal or power supply. This series turntable is equipped with two kinds of standard conductive slip rings for customers to choose, also can be customized according to customer needs.

5. The turntable adopts DSP control system developed by our company, equipped with RS232, RS485 communication interface, and can also be

customized according to customer needs, the system has a very friendly man-machine interface.

Specifications

Maximum heig	ht (mm):				
The height of the axis of the outer frame (mm):					642
Maximum width of rame shafting (mm):					888
Dimensions of base (mm):					712 X 460 (LXW)
Table flatness (mm):					0.05
The distance between the mesa and the axis of the outer frame (mm):					98
Mesa of magnetic flux leakage (mT):					0.5
Payload weigh	t (kg):				20kg
The weight of t	he turntable (kg):				280kg
Turntable Mod	el No.:	ER-ZX2V300T	ER-ZX2V360T		
Shafting catego	ory	Inside casing sha	aftThe casing outsid	e the shaft	
Mechanical Te	echnical Specific	ations			
Shafting perpe	ndicularity	±4"			
Shafting rotation	on accuracy	≤±2″	≤±3"		
ne moment of inertia of		Without load	0.06kgm2 (Duralumin table)		
			Decided by the load moment of inertia (acceleration is		
shafting		On load	Decided by the loa	ad moment of ine	ertia (acceleration is
shafting		On load	-		ertia (acceleration is d by the moment of inertia)
shafting		On load	equal to the motor	r moment divideo	-
shafting		On load	equal to the motor	r moment divideo	d by the moment of inertia)
shafting		On load	equal to the motor the motor can run	r moment divideo	d by the moment of inertia)
	hnical Specificat		equal to the motor the motor can run action	r moment divideo	d by the moment of inertia)
Electrical Tec			equal to the motor the motor can run action of peak torque.	r moment divideo	d by the moment of inertia) 10 minutes under the
Electrical Tec	n range	ions	equal to the motor the motor can run action of peak torque.	r moment divideo continuously for	d by the moment of inertia) 10 minutes under the
Electrical Tec Angular rotation Control position	n range	ions Continuous infi	equal to the motor the motor can run action of peak torque.	r moment divided continuously for Continuous in	d by the moment of inertia) 10 minutes under the nfinite
Electrical Tec Angular rotation Control position Rate range	n range n accuracy	ions Continuous infi ±5"	equal to the motor the motor can run action of peak torque.	Continuously for Continuously for ±5" 0.001°/s~±50	d by the moment of inertia) 10 minutes under the nfinite
Electrical Tec Angular rotation Control position Rate range	n range n accuracy	ions Continuous infi ±5" 0.001°/s~±800° w<1°/s, 5X10-3	equal to the motor the motor can run action of peak torque.	Continuously for Continuously for ±5" 0.001°/s~±50 w<1°/s, 5X10	d by the moment of inertia) 10 minutes under the nfinite 00° /s
Electrical Tec Angular rotation Control position Rate range	n range n accuracy	ions Continuous infi ±5" 0.001°/s~±800° w<1°/s, 5X10-3 1°/s≤w<10°/s, 5	equal to the motor the motor can run action of peak torque. nite	r moment divided continuously for Continuous in ±5" 0.001°/s~±50 w<1°/s, 5X10 e) 1°/s≤w<10°/s	d by the moment of inertia) 10 minutes under the nfinite 00° /s 0-3 (1° average)
Electrical Tec Angular rotation Control position Rate range Rate accuracy	n range n accuracy & stability	ions Continuous infi ±5" 0.001°/s~±800° w<1°/s, 5X10-3 1°/s≤w<10°/s, 5	equal to the motor the motor can run action of peak torque. nite ° /s 3 (1° average) 5X10-4 (10° average)	r moment divided continuously for Continuous in ±5" 0.001°/s~±50 w<1°/s, 5X10 e) 1°/s≤w<10°/s	d by the moment of inertia) 10 minutes under the nfinite 00° /s 0-3 (1° average) s, 5X10-4 (10° average)
Electrical Tech Angular rotation Control position Rate range Rate accuracy Optional temp	n range n accuracy & stability	ions Continuous infi ±5" 0.001°/s~±800° w<1°/s, 5X10-3 1°/s≤w<10°/s, 5	equal to the motor the motor can run action of peak torque. nite ? /s 6 (1° average) 5X10-4 (10° average) 55 (360° average)	r moment divided continuously for Continuous in ±5" 0.001°/s~±50 w<1°/s, 5X10 e) 1°/s≤w<10°/s	d by the moment of inertia) 10 minutes under the nfinite 00° /s 0-3 (1° average) s, 5X10-4 (10° average)
Electrical Tech Angular rotation Control position Rate range Rate accuracy Optional temp	n range n accuracy & stability	ions Continuous infi ±5" 0.001°/s~±800° w<1°/s, 5X10-3 1°/s≤w<10°/s, 5 10°/s≤w, 5X10- φ360mm	equal to the motor the motor can run action of peak torque. nite ° /s 3 (1° average) 5X10-4 (10° average) 55 (360° average) φ	r moment divided continuously for Continuous in ±5" 0.001°/s~±50 w<1°/s, 5X10 e) 1°/s≤w<10°/s 10°/s≤w, 5X1 300mm	d by the moment of inertia) 10 minutes under the nfinite 00° /s 0-3 (1° average) s, 5X10-4 (10° average)
Electrical Tech Angular rotation Control position Rate range Rate accuracy Optional temp Table-board	n range n accuracy & stability blate Diameter	ions Continuous infi ±5" 0.001°/s~±800° w<1°/s, 5X10-3 1°/s≤w<10°/s, 5 10°/s≤w, 5X10- φ360mm	equal to the motor the motor can run action of peak torque. nite ° /s 6 (1° average) 5X10-4 (10° average) 5X10-4 (10° average) φ(um alloy (surface ha	r moment divided continuously for Continuous in ±5" 0.001°/s~±50 w<1°/s, 5X10 e) 1°/s≤w<10°/s 10°/s≤w, 5X1 300mm	d by the moment of inertia) 10 minutes under the nfinite 00° /s 0-3 (1° average) s, 5X10-4 (10° average) 10-5 (360° average) face hardness up to HRC3
shafting Electrical Tec Angular rotation Control position Rate range Rate accuracy Optional temp Table-board Motor	n range n accuracy & stability blate Diameter	ions Continuous infi ±5" 0.001°/s~±800° w<1°/s, 5X10-3 1°/s≤w<10°/s, 5 10°/s≤w, 5X10- φ360mm Hard aluminu Inside casing	equal to the motor the motor can run action of peak torque. nite ? /s ? (1° average) 5X10-4 (10° average) 5X10-4 (10° average) (5 (360° average) (0) (0) (0) (0) (0) (0) (0) (0) (0) (0	r moment divided continuously for Continuously for ±5" 0.001°/s~±50 w<1°/s, 5X10 e) 1°/s≤w<10°/s 10°/s≤w, 5X1 300mm rd treatment, sur	d by the moment of inertia) 10 minutes under the nfinite 00° /s 0-3 (1° average) s, 5X10-4 (10° average) 10-5 (360° average) face hardness up to HRC3

2. Speed accuracy, stability and flatness of the table can be selected according to customer requirements, up to 5

times.

3. Northward guiding mirror is available.

4. According to user requirements, British Renishaw circular grating or German Heidenhain encoder can be configured as position feedback components (standard for Heidenhain encoder).

5. The shaft rotation accuracy and verticality can be customized according to user requirements.

6. Table diameter can be customized within 360mm according to user requirements.

Conductive slip ring

1. Ring number: (can be customized according to user requirements)

56Ring 36Ring

1~36 channel, 2A, twin twist shield; 1~24 channel, 2A, twin twist shield

37~56 channel, 5A, power cord. 25~36 lines, 5A, power Line

2. Contact resistance change value: static ≤0.005Ω dynamic ≤0.01 Ω

3. Insulation resistance between conductive slip rings: ≥300MΩ, 500V; Contact resistance of conductive slip ring: ≤0.1Ω

4. Working humidity: ≤85%.

5. Power supply: 220V ±10%, 50Hz/16A